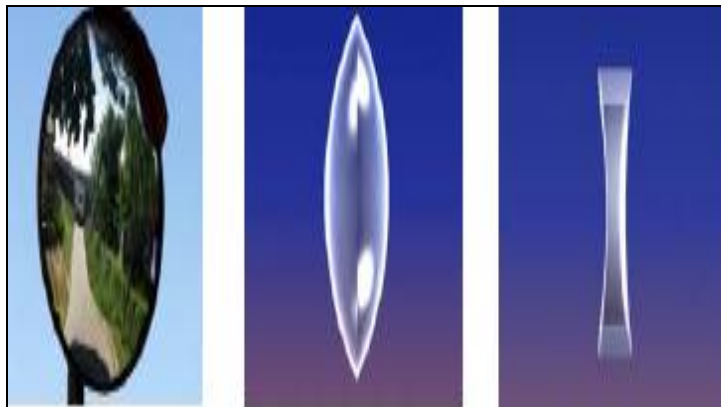


**Kirkuk University  
Science College  
Physics Department**

***Lectures of  
GEOMETRIC OPTICS  
Lecture – 3 –***



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### Lecture 3: Spherical Mirrors - Concave Mirror – Part 2

#### 3 – 1 Ray Diagrams - Concave Mirror

#### 3 – 2 The Mirror Equation - Concave Mirror

#### 3-3 Derivation of Spherical Mirror Equation –Concave Mirror

#### 3 – 4 The +/- Sign Conventions - Concave Mirror

#### 3 – 1 Ray Diagrams - Concave Mirror

##### Case 1: The object is located *beyond C*

- When the object is located at a location beyond the center of curvature, the image will always be located somewhere in **between the center of curvature and the focal point**, as shown in Fig.(3-1) .

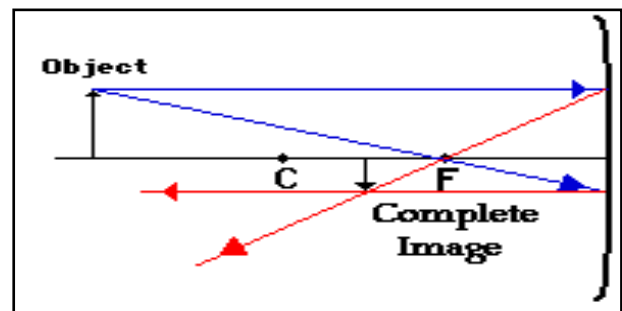
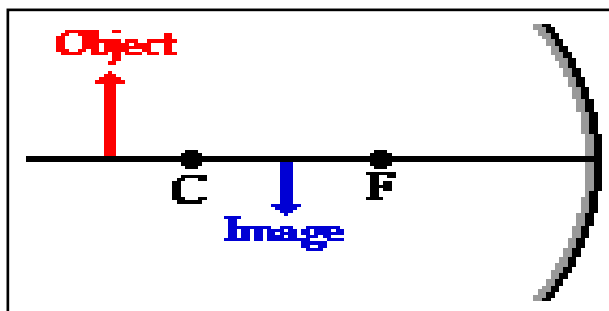
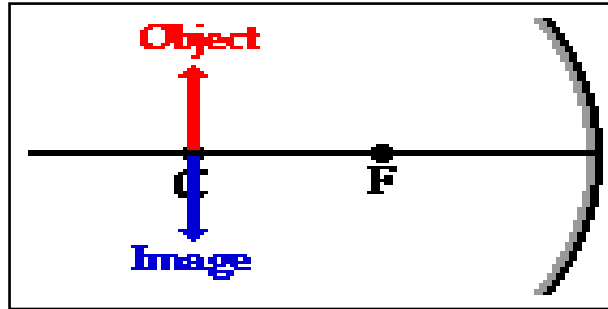


Fig. (3-1): The object is located *beyond C*

- Regardless of exactly where the object is located, the image will be located in the specified region.
- In this case, the image will be an **inverted image**.
- In this case, the image is **reduced in size**; in other words, the image dimensions are smaller than the object dimensions.
- The term magnification was introduced; the **magnification** is the ratio of the height of the image to the height of the object.
- In this case, the absolute value of the magnification is **less than 1**.
- Finally, the image is a **real image**.

### **Case 2:** The object is located at C

- When the object is located at the center of curvature, the image will also be located **at the center of curvature**, as shown in Fig.(3-2) and Fig.(3-4a) .



**Fig. (3-2): The object is located at C**

- In this case, the image will be **inverted**.
- The image dimensions are equal to the object dimensions.
- The absolute value of the magnification is **equal to 1**.
- Finally, the image is a **real image**.

### Case 3: The object is located between C and F

- When the object is located *in front of* the center of curvature, the image will be located **beyond the center of curvature**, as shown in Fig.(3-3) and Fig.(3-4b).

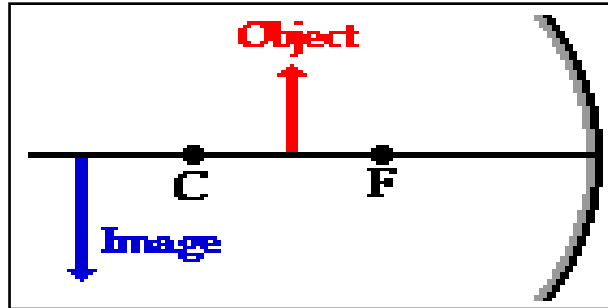
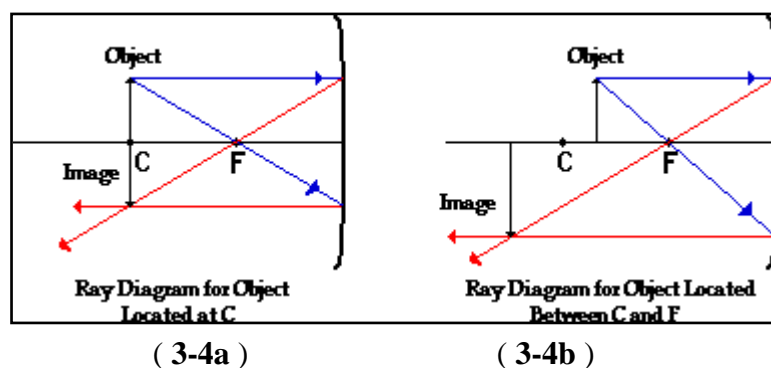


Fig. (3-3): The object is located between C and F

- Regardless of exactly where the object is located between C and F, the image will be located somewhere *beyond* the center of curvature.
- In this case, the image will be **inverted**.
- The image dimensions are larger than the object dimensions.
- The absolute value of the magnification is **greater than 1**.
- Finally, the image is a **real image**.



( 3-4a )

( 3-4b )

( 3-4a ) :The object is located at C

(3-4b) : The object is located between C and F

### Case 4: The object is located at F

- When the object is located at the focal point, **no image is formed** as shown in Fig.(3-5).

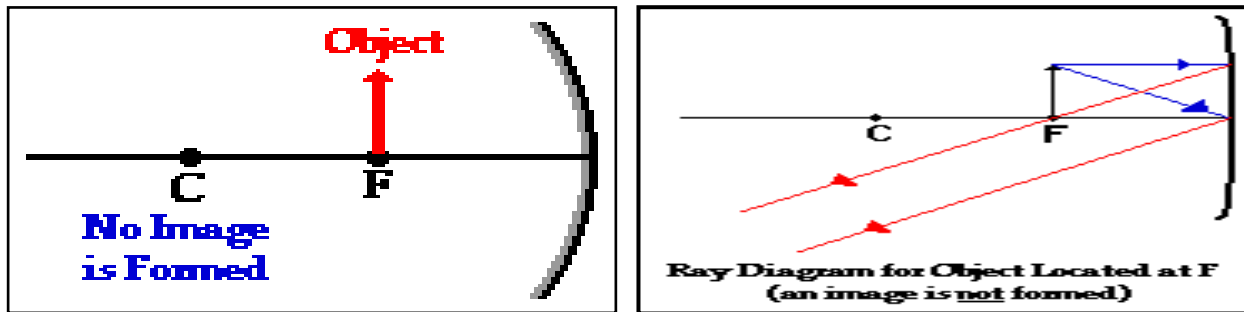


Fig. (3-5): The object is located at F

- Light rays from the same point on the object will reflect off the mirror and neither converge nor diverge.
- After reflecting, the light rays are traveling parallel to each other and do not result in the formation of an image.

### **Case 5:** The object is located *in front of F*

- When the object is located at a location in front of the focal point, the image will always be located somewhere **on the opposite side of the mirror**, as shown in Fig.(3-6).

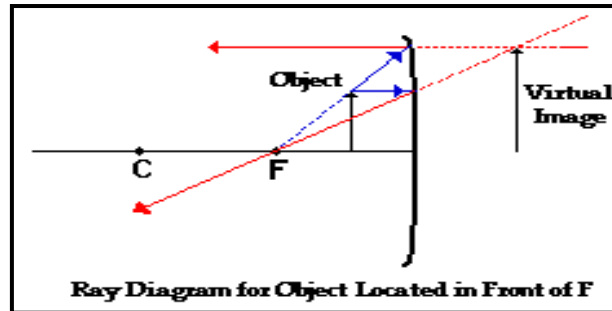


Fig. (3-6): The object is located in front of F

- Regardless of exactly where in front of **F** the object is located, the image will always be located behind the mirror.
- In this case, the image will be an **upright image**.
- In this case, the image is **magnified**; in other words, the image dimensions are greater than the object dimensions.
- The magnification is **greater than 1**.
- Finally, the image is a **virtual image**.

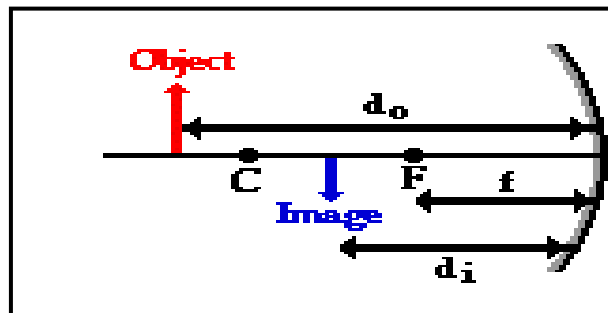
### **3 – 2 The Mirror Equation - Concave Mirror**

- Ray diagrams can be used to determine the image location, size, orientation and type of image formed of objects when placed at a given location in front of a concave mirror.
- Ray diagrams provide useful information about object-image relationships, yet fail to provide the information in a quantitative form.
- While a ray diagram may help one determine the approximate location and size of the image, it will not provide numerical information about image distance and image size.
- To obtain this type of numerical information, it is necessary to use the **Mirror Equation** and the **Magnification Equation**.

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- The mirror equation expresses the quantitative relationship between the object distance ( $d_o$ ), the image distance ( $d_i$ ), and the focal length ( $f$ ).
- The equation is stated as follows that shown in Fig.(3-7):

$$\boxed{\frac{1}{f} = \frac{1}{d_o} + \frac{1}{d_i} \dots(3-1a)} \quad \text{or} \quad \boxed{\frac{2}{R} = \frac{1}{d_o} + \frac{1}{d_i} \dots(3-1b)}$$



**Fig. (3-7): The Variables of Mirror Equation – Concave Mirror**

- The magnification equation relates the ratio of the image distance ( $d_i$ ) and object distance ( $d_o$ ) to the ratio of the image height ( $h_i$ ) and object height ( $h_o$ ).
- The magnification equation is stated as follows:

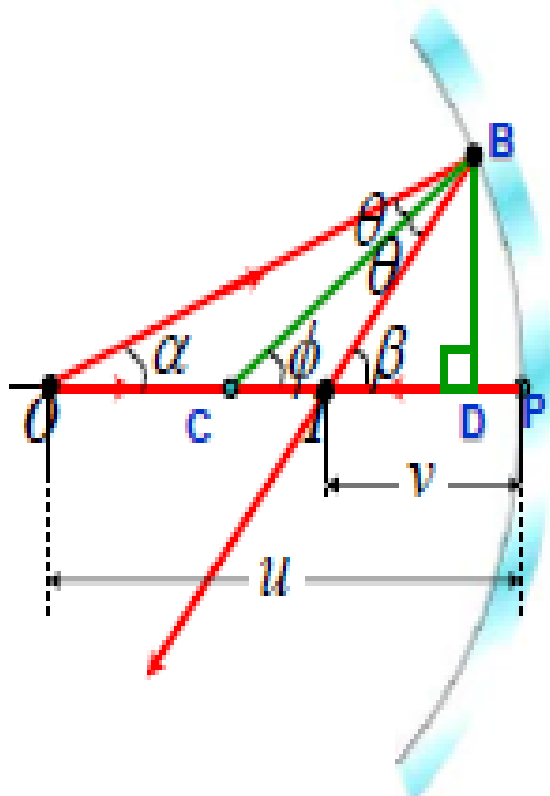
$$\boxed{M = \frac{h_i}{h_o} = -\frac{d_i}{d_o} \dots(3-2)}$$

- These two equations can be combined to yield information about the image distance and image height if the object distance, object height, and focal length are known.
- As a demonstration of the effectiveness of the mirror equation and magnification equation, consider the examples and its solution in the next lecture.



**3 – 3 Derivation of Spherical mirror equation-Concave Mirror**

- Figure below shows an object  $O$  at a distance  $u$  and on the principal axis of a concave mirror. A ray from the object  $O$  is incident at a point  $B$  which is close to the pole  $P$  of the mirror.



- From the figure,

$$\triangle BOC \Rightarrow \phi = \alpha + \theta \quad \text{---(1)}$$

$$\triangle BCI \Rightarrow \beta = \phi + \theta \quad \text{---(2)}$$

then, eq. (1)-(2) :

$$\phi - \beta = \alpha - \phi$$

$$\alpha + \beta = 2\phi \quad \text{---(3)}$$

By using  $\triangle BOD$ ,  $\triangle BCD$  and  $\triangle BID$  thus

$$\tan \alpha = \frac{BD}{OD}; \tan \phi = \frac{BD}{CD}; \tan \beta = \frac{BD}{ID}$$

- By considering point  $B$  very close to the pole  $P$ , hence

$$\tan \alpha \approx \alpha; \tan \phi \approx \phi; \tan \beta \approx \beta$$

$$OD \approx OP = u; CD \approx CP = r; ID \approx IP = v$$

then

$$\left. \begin{aligned} \alpha &= \frac{BD}{u} ; \phi = \frac{BD}{r} ; \beta = \frac{BD}{v} \end{aligned} \right\} \text{Substituting this value in eq. (3)} \quad 26$$

therefore

$$\frac{BD}{u} + \frac{BD}{v} = 2 \left( \frac{BD}{r} \right)$$

$$\frac{1}{u} + \frac{1}{v} = \frac{2}{r} \quad \text{where } r = 2f$$

$$\boxed{\frac{1}{f} = \frac{1}{u} + \frac{1}{v}}$$

Equation (formula) of spherical mirror

### **3 – 4 The +/- Sign Conventions – Concave Mirror**

- The sign conventions for the given quantities in the mirror equation and magnification equations are as follows:-
- $(f)$  is  $(+)$  if the mirror is a (concave mirror).
  - $(d_i)$  is  $(+)$  if the image is a real image and located on the object's side of the mirror.
  - $(d_i)$  is  $(-)$  if the image is a virtual image and located behind the mirror.
  - $(h_i)$  is  $(+)$  if the image is an upright image (and therefore, also virtual).
  - $(h_i)$  is  $(-)$  if the image is an inverted image (and therefore, also real).
  - $(R)$  is  $(+)$  if center of curvature is in front of mirror (concave mirror).
  - $(M)$  is  $(+)$ , image is **upright**.
  - $(M)$  is  $(-)$ , image is **inverted**.