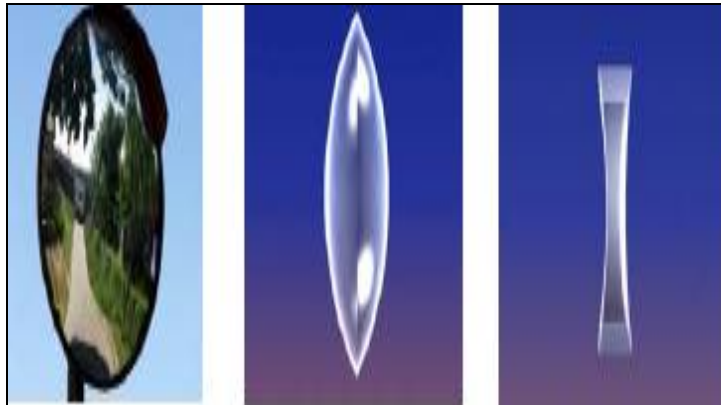


**Kirkuk University**

**Science College**

**Physics Department**

***Lectures of***  
***GEOMETRIC OPTICS***  
***Lecture – 12 –***



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## Lecture 12: Converging Lenses ( double convex lens ) – Part 2

### 12 - 1 Ray Diagrams of Converging Lenses (double convex lens)

### 12 - 2 The Mathematics of Converging Lenses (double convex lens)

### 12 – 3 The +/- Sign Conventions for Converging Lenses (double convex lens)

#### 12 – 1 Ray Diagrams of Converging Lenses (double convex lens)

##### Case 1: The object is located *beyond* $2F$

- When the object is located at a location beyond the  $2F$  point, the image will always be located somewhere in between the  $2F$  point and the focal point ( $F$ ) on the other side of the lens, as shown in Fig.(12-1).

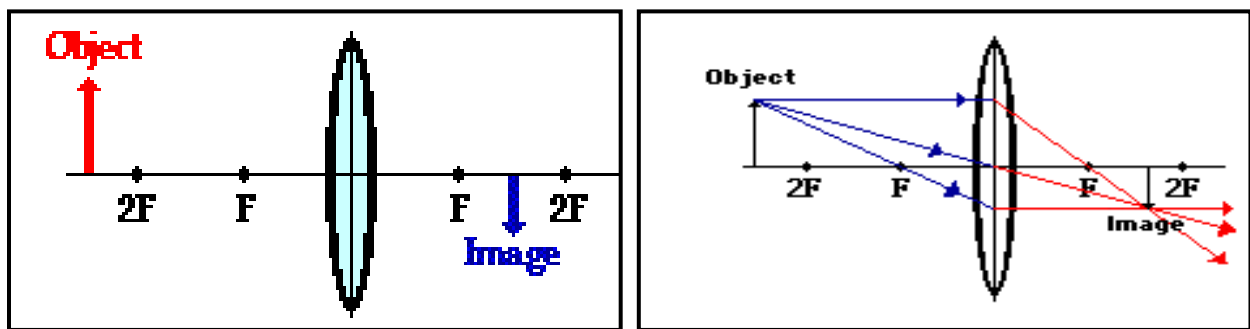


Fig.(12-1) : The object is located at a location beyond the  $2F$  point

- Regardless of exactly where the object is located, the image will be located in this specified region.
- In this case, the image will be an **inverted image**.
- In this case, the image is **reduced in size**; in other words, the image dimensions are smaller than the object dimensions.
- Earlier in past lectures, the term magnification was introduced; the **magnification** is the ratio of the height of the image to the height of the object.
- In this case, the magnification is a number with an absolute value **less than 1**.
- Finally, the image is a **real image**.

### **Case 2:** The object is located at $2F$

- When the object is located at the  $2F$  point, the image will also be located at the  $2F$  point on the other side of the lens, as shown in Fig.(12-2) and Fig.(12-4a).

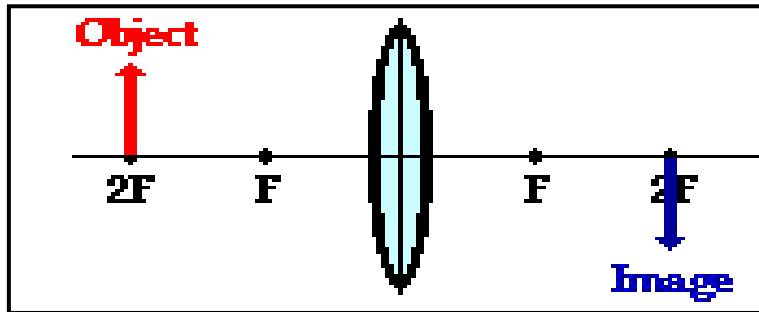


Fig.(12-2) : The object is located at the  $2F$  point

- In this case, the image will be **inverted**.
- The image dimensions are equal to the object dimensions.
- The absolute value of the magnification is **exactly 1**.
- Finally, the image is a **real image**.

### Case 3: The object is located between $2F$ and $F$

- When the object is located *in front of* the  $2F$  point, the image will be located *beyond* the  $2F$  point on the other side of the lens, as shown in Fig. (12-3) and Fig.(12-4b) .

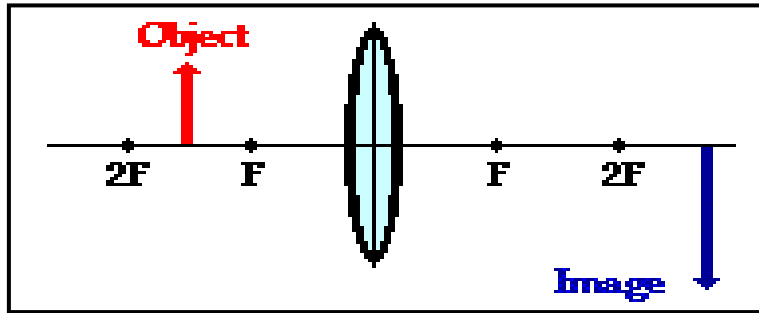
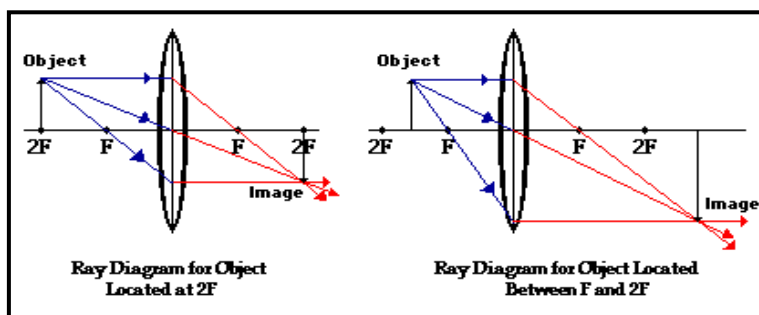


Fig.(12-3) : The object is located *in front of* the  $2F$  point

- Regardless of exactly where the object is located between  $2F$  and  $F$ , the image will be located in the specified region.
- In this case, the image will be **inverted**.
- The image dimensions are larger than the object dimensions.
- The absolute value of the magnification is **greater than 1**.
- Finally, the image is a **real image**.



(12-4a)

(12- 4b)

Fig.(12-4a) : The object is located at the  $2F$  point

Fig.(12-4b) : The object is located *in front of* the  $2F$  point

### Case 4: The object is located at F

- When the object is located at the focal point, no image is formed, as shown in Fig.(12-5).

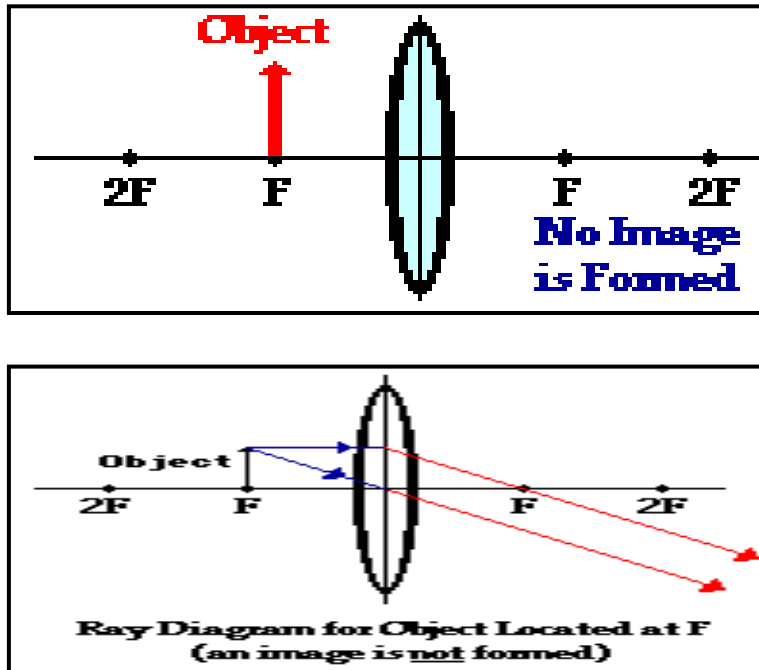


Fig.(12-5) : The object is located at the F point

- As discussed in past lectures, the refracted rays neither converge nor diverge.
- After refracting, the light rays are traveling parallel to each other and cannot produce an image.

### Case 5: The object is located *in front of F*

- When the object is located at a location in front of the focal point, the image will always be located somewhere on the same side of the lens as the object, as shown in Fig.(12-6).

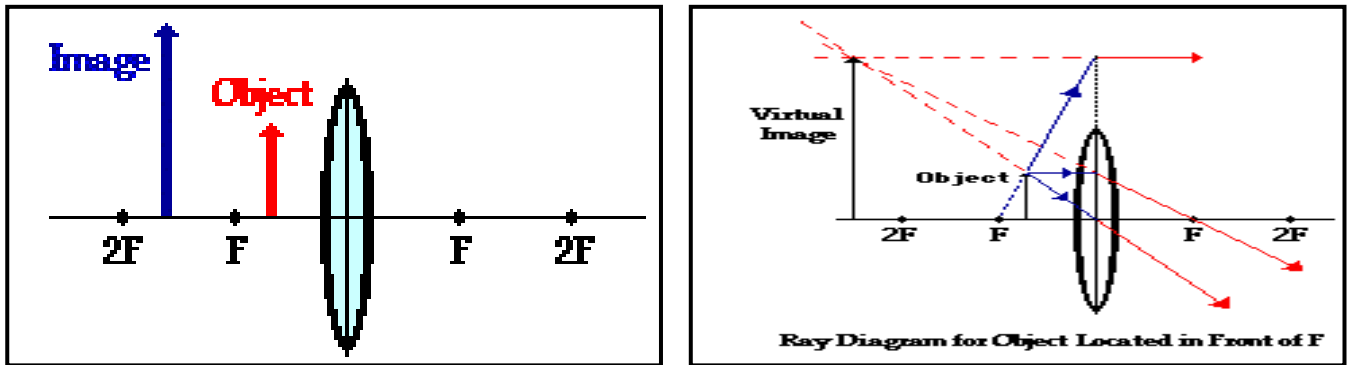


Fig.(12-6) : The object is located at a location in front of the focal point

- Regardless of exactly where in front of **F** the object is located, the image will always be located on the object's side of the lens and somewhere further from the lens.
- In this case, the image will be an **upright image**.
- In this case, the image is **enlarged**; in other words, the image dimensions are greater than the object dimensions.
- The magnification is **greater than 1**.
- Finally, the image is a **virtual image**.
- Light rays diverge upon refraction; for this reason, the image location can only be found by extending the refracted rays backwards on the object's side the lens.
- The point of their intersection is the virtual image location.

### **12 - 2 The Mathematics of Converging Lenses (double convex lens)**

- Ray diagrams can be used to determine the image location, size, orientation and type of image formed of objects when placed at a given location in front of a lens.
- The use of these diagrams was demonstrated earlier in past lectures for both converging and diverging Mirrors.
- Ray diagrams provide useful information about object-image relationships, yet fail to provide the information in a quantitative form.
- While a ray diagram may help one determine the approximate location and size of the image, it will not provide numerical information about image distance and image size.
- To obtain this type of numerical information, it is necessary to use the **Lens Equation** and the **Magnification Equation**.

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- The lens equation expresses the quantitative relationship between the object distance ( $d_o$ ), the image distance ( $d_i$ ), and the focal length ( $f$ ).
- The equation is stated as follows in Fig.(12-7):

$$\frac{1}{f} = \frac{1}{d_o} + \frac{1}{d_i} \dots (12-1)$$

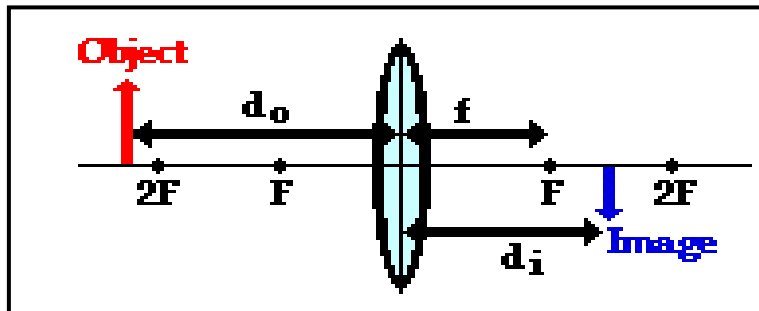


Fig.(12-7) : The Variables of Lens Equation – Converging Lens

- The magnification equation relates the ratio of the image distance and object distance to the ratio of the image height ( $h_i$ ) and object height ( $h_o$ ).
- The magnification equation is stated as follows:

$$M = \frac{h_i}{h_o} = -\frac{d_i}{d_o} \dots (12-2)$$

- These two equations can be combined to yield information about the image distance and image height if the object distance, object height, and focal length are known.
- As a demonstration of the effectiveness of the lens equation and magnification equation, consider the examples and its solution in the next lecture.



### *12 – 3 The +/- Sign Conventions for Converging Lenses (double convex lens)*

➤ The sign conventions for the given quantities in the lens equation and magnification equations are as follows:-

- $(f)$  is  $(+)$  if the lens is a (converging lens).
- $(d_i)$  is  $(+)$  if the image is a real image and located in back of lens (or on the other side of the lens).
- $(d_i)$  is  $(-)$  if the image is a virtual image and located in front of lens (or on the same side of the lens as the object).
- $(h_i)$  is  $(+)$  if the image is an upright image (and therefore, also virtual).
- $(h_i)$  is  $(-)$  if the image is an inverted image (and therefore, also real).
- $(M)$  is  $(+)$ , image is **upright**.
- $(M)$  is  $(-)$ , image is **inverted**.